

## PTM Automation Servo Gripper



Manufacturer: PTM Automation  
 Model Number: PTM-Automation-Servo-Gripper  
 Web Address: [www.ptm-automation.de](http://www.ptm-automation.de)

The PTM Servo Gripper with serial interface optimizes the sensitive handling of the various products and devices in the laboratory automation as well as applications in the general automation industry area

### Gripper: Commands

- ▶ **GetStatus( )** - Get the status of the servo gripper.
- ▶ **GetPosition( )** - Get the position of the servo gripper.
- ▶ **Position( position )** - Position the servo gripper to the set position.

|          |         |   |
|----------|---------|---|
| position | Integer | Position of the servo gripper. Range of values: 0 to 500. |
|----------|---------|---|

- ▶ **Grip( position, force )** - Close the gripper and grip the object.

|          |         |   |
|----------|---------|---|
| position | Integer | Position of the servo gripper. Range of values: 0 to 500. |
|----------|---------|---|

|       |         |   |
|-------|---------|---|
| force | Integer | Force of the servo gripper. Range of values: 3 to 50. |
|-------|---------|---|

- ▶ **Home( position )** - Home the gripper to find the reference position.

|          |         |   |
|----------|---------|---|
| position | Integer | Position of the servo gripper. Range of values: 0 to 500. |
|----------|---------|---|

### Gripper Error

- 🔥 **GripperError( code )** - Error occurred during command execution.

|      |         |             |
|------|---------|-------------|
| code | Integer | Error code. |
|------|---------|-------------|

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